

1.7 Motor Control Relays



Application	Types	Output	DC ratings	Mounting
DC Motor controller	CMC1	2x MOSFET	16 A (20 A) / 24 V	DIN
	CMC15	2x MOSFET H bridge	10 A (20 A) / 24 V	DIN
	CMC16	2x MOSFET H bridge	10 A (20 A) / 24 V	DIN
DC Motor control relay	KDM3-24	1x PNP & 1x NPN	3 A / 32 V	S7-C

CMC1

DC Motor controller with adjustable start and breaking ramps for DC motors up to 384W

Type: CMC1/DC12-24V

The CMC is a control device for DC motors and permits operation in both rotating directions, i. e. the rotating direction can be reversed with the input signal. Alternatively, two motors can be operated in the same direction.

The CMC1 allows also to control lamps or electromagnets. The start and breaking ramps of the connected loads can be adjusted by two potentiometers in the time range 0 - 4 seconds.

Maximum load	16 A / 24 V
Outputs	Drive
Туре	MOSFET
Nominal switching current	16 A
nrush current	20 A (short-term)
Nominal voltage	24 V
Switching power	384 W
Control input V _n =	12-24 V
Nominal operating voltage range (DC)	12 – 24 V
Admissible voltage range (DC)	8 – 28 V
Current consumption	DC
12 V	3 mA
24 V	6 mA
Power supply	
Nominal operating voltage (DC)	12 – 24 V
Operating voltage (DC)	8 – 28 V
Max. current consumption without load	10 mA
Max. power consumption	DC
12 V	120 mW
24 V	240 mW
General Specifications	
Ambient temperature storage/operation	-40 - +85°C / -25 - +60°C
Connection terminals	Screw terminal 2.5 mm ²
DC voltage endurance at rated load	> 100 000 h (at 25 °C)
ngress protection degree	IP 20
Vounting	DIN rail TS35
Housing material	Aluminium
Weight	80 g
Standard types	

CMC1/DC12-24V

Standard types

DC 12-24





Connection diagram



Function diagramm



Dimensions [mm]



Technical approvals, conformities



CMC15

DC Motor controller with adjustable start and breaking ramps and speed control by 0 ... 10 V signal for DC motors up to 240W

Type: CMC15/DC12-24V

The CMC15 is a control device for DC motors and permits operation in both rotating directions, i. e. the rotating direction can be reversed with the input signal. Alternatively two motors can be operated in the same rotating direction. The motor speed is set by a 0 - 10 V signal.

Maximum load	10 A / 24 V	
Outputs	Drive	
Туре	MOSFET H bridge	
Nominal switching current	10 A	
Inrush current	20 A / max. 3 s	
Nominal voltage	24 V	
Switching power	240 W	
Analogue inputs		
Nominal operating voltage range (DC)	0 – 10 V	
Resolution	8 Bit	Co
Input impedance	55 kΩ	
Power supply		
Nominal operating voltage (DC)	12 – 24 V	
Operating voltage (DC)	8 – 28 V	
Max. current consumption without load	10 mA	
Max. power consumption	DC	
12 V	120 mW	
24 V	240 mW	
Time response		
Start ramp	0 – 2 s	
Breaking ramp	0 – 2 s	
General Specifications		Fu
Ambient temperature storage/operation	-40 – +85°C / -25 – +60°C	
Connection terminals	Screw terminal 2.5 mm ²	
DC voltage endurance at rated load	> 100 000 h (at 25 °C)	
Ingress protection degree	IP 20	
Mounting	DIN rail TS35	
Housing material	Aluminium	
Weight	80 g	
Standard types		
DC 12-24	CMC15/DC12-24V	





Connection diagram



Function diagramm



Dimensions [mm]



Technical approvals, conformities



Relays 1.7

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CMC16

DC Motor controller with adjustable start and breaking ramps and speed control by 4 ... 20 mA signal for DC motors up to 240W

Type: CMC16/DC12-24V

The CMC16 is a control device for DC motors and permits operation in both rotating directions, i. e. the rotating direction can be reversed with the input signal. Alternatively two motors can be operated in the same rotating direction. The motor speed is set by a 4 - 20 mA signal.

Maximum load	10 A / 24 V	
Outputs	Drive	
Туре	MOSFET H bridge	
Nominal switching current	10 A	
Inrush current	20 A / max. 3 s	
Nominal voltage	24 V	
Switching power	240 W	
Analogue inputs		
Nominal operating voltage range (DC)	4 – 20 mA	
Resolution	8 Bit	C
Input impedance	190 Ω	
Power supply		
Nominal operating voltage (DC)	12 – 24 V	
Operating voltage (DC)	8 – 28 V	
Max. current consumption without load	10 mA	
Max. power consumption	DC	
12 V	120 mW	
24 V	240 mW	
Time response		
Start ramp	0 – 2 s	
Breaking ramp	0 – 2 s	_
General Specifications		F
Ambient temperature storage/operation	-40 – +85°C / -25 – +60°C	
Connection terminals	Screw terminal 2.5 mm ²	
DC voltage endurance at rated load	> 100 000 h (at 25 °C)	
Ingress protection degree Mounting Housing material	IP 20	
	DIN rail TS35	
	Aluminium	
Weight	80 g	
Standard types		
DC 12-24	CMC16/DC12-24V	





Connection diagram



Function diagramm



Dimensions [mm]



Technical approvals, conformities



KDM 3-24

DC Motor control relay with brake function, DC 24 V 1 high side switch and 1 N-channel brake switch

Type: KDM 3-24/DC12-24V R

Solid state relay for DC-motor control and similar applications 1 high side + 1 N channel transistor switch All overload and short circuit protected Adjustable or disabled brake function by external resistor or jumper LED status indicator Pluggable module

Maximum load

Outputs	Drive	Brake
Type: Power MOS FET	High side	N-channel
Max. switching current	3 A	3 A, 10 sec
Max. continuous current	3 A (5 A) ¹⁾	2 A
Max. inrush current, 1 sec ²⁾	20 A	7
Switching voltage range	10 32 V	10 32 V
Max. Load	100 W	65 W
Thermal overload protection ²⁾	self restoring	self restoring
Over current limiting ²⁾	typ. 35 A	7 14 A
Clamp voltage	typ. 58 V	60 70 V
Max. inductive switch-off energy ²⁾	1 Ws single pulse	0.4 Ws single pulse
ON resistance @ 25 °C	≤ 50 mΩ	≤ 100 mΩ
Leakage current	≤ 10 µA	

3 A / 32 V

DC 12-24 V

9... 28 V

2 / 6.5 mA

protected

25 / 160 mW

-40 ... +85°C / -25 ... +60°C

KDM3-24/DC12-24V R

IP 40 when the device is plugged in

 $\leq 2 V$

1 ms 1 ms

Lexan 27 g

S7-C

 $^{1)}$ Repetitive operation: When the ratio t_{pulse} / t_{cycle} is a low value then the current can be increased up to 5 A @ T_{A} \leq 50 °C.

²⁾ Not for continous repetitive operation

Control input V_N = Operating voltage range Release voltage

Typical input current @ 12 / 24 V Power consumption @ 12 / 24 V Polarity reversal

General Specifications

Ambient temperature storage/operation
ON delay
Release time
Ingress protection degree
Housing material
Weight

Standard types

DC 12-24

Accessories

Socket:

Application example

Four quadrant (forward / reversed) motor control



Operating with brake resistors (on 2–3) is not recommended in this application.





Connection diagram



Function diagramm



Output current vs. duty cycle

Dimensions [mm]



Technical approvals, conformities





Notes